CMSC 478 Lecture 3 KMA Solaiman

## Supervised Learning: Classification, Perceptrons

Some slides are slightly adapted from Chris Re', Stanford ML

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## Visual version of linear regression: Learning



Let  $h_{\theta}(x) = \sum_{j=0}^{d} \theta_j x_j$  want to choose  $\theta$  so that  $h_{\theta}(x) \approx y$ . One popular idea called **least squares** 

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$

Choose

$$\theta = \underset{\theta}{\operatorname{argmin}} J(\theta).$$

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Solving the least squares optimization problem.

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## Gradient Descent

Animation



## Gradient Descent

- $\mathcal{J}(\theta) = (\theta 4)^2 + 1$
- Find the weight (value of  $\theta$ ) that minimizes the loss  ${\mathcal J}$
- $\mathcal{J}'(\theta) = ?$
- *θ* = 2.5
- given the current value of w, adjusting  $\theta$  by an amount that has the negative of the sign of  $\mathcal{J}'(\theta)$ leads to a smaller value of  $\mathcal{J}$ .



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## Gradient Descent

	size	bedrooms	lot size		Price
$x^{(1)}$	2104	4	45k	y <sup>(1)</sup>	400
$x^{(2)}$	2500	3	30k	y <sup>(2)</sup>	900

What's a prediction here?

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right)^{2}.$$

$$h(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3.$$

$$\theta^{(0)} = 0$$
  
$$\theta_j^{(t+1)} = \theta_j^{(t)} - \alpha \frac{\partial}{\partial \theta_j} J(\theta^{(t)}) \qquad \text{for } j = 0, \dots, d.$$

$$heta_j^{(t+1)} = heta_j^{(t)} - lpha rac{\partial}{\partial heta_j} J( heta^{(t)}) ext{ for } j = 0, \dots, d.$$

Note that  $\alpha$  is called the **learning rate** or **step size**.

Let's compute the derivatives...

$$\begin{split} \frac{\partial}{\partial \theta_j} J(\theta^{(t)}) &= \sum_{i=1}^n \frac{1}{2} \frac{\partial}{\partial \theta_j} \left( h_\theta(x^{(i)}) - y^{(i)} \right)^2 \\ &= \sum_{i=1}^n \left( h_\theta(x^{(i)}) - y^{(i)} \right) \frac{\partial}{\partial \theta_j} h_\theta(x^{(i)}) \end{split}$$

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For our *particular*  $h_{\theta}$  we have:

$$h_{\theta}(x) = \theta_0 x_0 + \theta_1 x_1 + \dots + \theta_d x_d \text{ so } \frac{\partial}{\partial \theta_j} h_{\theta}(x) = x_j$$

Thus, our update rule for component *j* can be written:

$$\theta_{j}^{(t+1)} = \theta_{j}^{(t)} - \alpha \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) x_{j}^{(i)}$$

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We write this in *vector notation* for j = 0, ..., d as:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) x^{(i)}.$$

Saves us a lot of writing! And easier to understand ... eventually.

## Batch Versus Stochastic Minibatch: Motivation

Consider our update rule:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha \sum_{i=1}^{n} \left( h_{\theta}(x^{(i)}) - y^{(i)} \right) x^{(i)}.$$

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- In some modern applications (more later) n may be in the billions or trillions!
  - E.g., we try to "predict" every word on the web.
- Idea Sample a few points (maybe even just one!) to approximate the gradient called Stochastic Gradient (SGD).
  - SGD is the workhorse of modern ML, e.g., pytorch and tensorflow.

#### Stochastic Minibatch

- ▶ We randomly select a **batch** of  $B \subseteq \{1, ..., n\}$  where |B| < n.
- We approximate the gradient using just those B points as follows (vs. gradient descent)

$$\frac{1}{|B|} \sum_{j \in B} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)} \text{ v.s. } \frac{1}{n} \sum_{j=1}^{n} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

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So our update rule for SGD is:

All minibatches are used for each iteration, or epoch and then start the next one

$$\theta^{(t+1)} = \theta^{(t)} - \alpha_B \sum_{j \in B} \left( h_\theta(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

▶ NB: scaling of |B| versus *n* is "hidden" inside choice of  $\alpha_B$ .

#### Stochastic Minibatch vs. Gradient Descent

Recall our rule B points as follows:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha_B \sum_{j \in B} \left( h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

- If  $|B| = \{1, \ldots, n\}$  (the whole set), then they coincide.
- Smaller B implies a lower quality approximation of the gradient (higher variance).
- Nevertheless, it may actually converge faster! (Case where the dataset has many copies of the same point-extreme, but lots of redundancy)

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- Nevertheless, it may actually converge faster! (Case where the dataset has many copies of the same point—extreme, but lots of redundancy)
- In practice, choose B proportional to what works well on modern parallel hardware (GPUs).

Supervised Learning and Classification

► Perceptrons

► Linear Regression via a Probabilistic Interpretation

Logistic Regression

# Linear Classification: Mushroom and Goats

	color	width	height	label
0	-0.311688	0.358501	0.936567	edible
1	-0.472327	0.817906	0.468387	poisonous

 $extsf{sign}(w_c * extsf{color} + w_w * extsf{width} + w_h * extsf{height}) \\ extsf{sign}(0 * -0.472327 + 1 * 0.817906 - 1 * 0.468387) = extsf{sign}(0.349519) = +1 \\ extsf{sign}(0 * -0.311688 + 1 * 0.358501 - 1 * 0.936567) = extsf{sign}(-0.578066) = -1 \end{aligned}$ 



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**0** 0.048589

1

2

3

4

5

6

7

8

9

10

0.200023

1.595538

1.315929

1.087080

0.512235

0.265039

1.606480

0.977585

1.908708

2.503476



## Classification

Given a training set  $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\}$  let  $y^{(i)} \in \{0, 1\}$ . Why not use regression, say least squares? A picture ...

## Loss Function for Classification: 0-1 Loss

$L_{0-1}$	$\hat{y} = -1$	$\hat{y} = 1$
y = -1	0	1
y = 1	1	0

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$$L_{0-1}(y, \mathbf{w} \cdot \mathbf{x}) = egin{cases} 0 & ext{if } y st \mathbf{w} \cdot \mathbf{x} > 0 \ 1 & ext{otherwise} \end{cases}$$

## Loss Function for Classification: 0-1 Loss



**Perceptron Loss** 

$$L_P(y, \mathbf{w} \cdot \mathbf{x}) = egin{cases} 0 & ext{if } y st \mathbf{w} \cdot \mathbf{x} > 0 \ -y st \mathbf{w} \cdot \mathbf{x} & ext{otherwise} \end{cases}$$



```
def perceptron(df, label = 'y', epochs = 100, bias = True):
if bias:
    df = df.copy()
    df.insert(0, '_x0_', 1)
w = np.zeros(len(df.columns) - 1)
features = [column for column in df.columns if column != label]
for _ in range(epochs):
    errors = 0
    for _, row in df.iterrows():
        x = row[features]
        y = row[label]
        if y * np.dot(w, x) <= 0:</pre>
            W = W + Y * X
            errors += 1
        yield w.copy()
    if errors == 0:
        break
```



Graph of Iris Dataset with logistic regression

Given a training set  $\{(x^{(i)}, y^{(i)}) \text{ for } i = 1, ..., n\}$  let  $y^{(i)} \in \{0, 1\}$ . Want  $h_{\theta}(x) \in [0, 1]$ . Let's pick a smooth function:

$$h_{\theta}(x) = g(\theta^{T} x)$$

Here, g is a link function. There are many...

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$$g(z)=\frac{1}{1+e^{-z}}.$$



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How do we interpret  $h_{\theta}(x)$ ?

$$P(y = 1 \mid x; \theta) = h_{\theta}(x)$$
  
 $P(y = 0 \mid x; \theta) = 1 - h_{\theta}(x)$ 

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Let's write the Likelihood function. Recall:

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Then,

$$L(\theta) = P(y \mid X; \theta) = \prod_{i=1}^{n} p(y^{(i)} \mid x^{(i)}; \theta)$$

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How do we go to a cost function from P (y I X;  $\theta$ ) ?

We need to go back to Maximum Likelihood Estimation that we saw before at the beginning of this lecture.

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Taking logs to compute the log likelihood  $\ell(\theta)$  we have:

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^{n} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$

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#### Now to solve it...

$$\ell(\theta) = \log L(\theta) = \sum_{i=1}^{n} y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log(1 - h_{\theta}(x^{(i)}))$$

We maximize for  $\theta$  but we already saw how to do this! Just compute derivative, run (S)GD and you're done with it!

**Takeaway:** This is *another* example of the max likelihood method: we setup the likelihood, take logs, and compute derivatives.

Time Permitting: There is magic in the derivative...

Even more, the batch update can be written in a *remarkably familiar* form:

$$\theta^{(t+1)} = \theta^{(t)} + \sum_{j \in B} (y^{(j)} - h_{\theta}(x^{(j)})) x^{(j)}$$

We sketch why (you can check!) We drop superscripts to simplify notation and examine a single data point:

$$y \log h_{\theta}(x) + (1 - y) \log(1 - h_{\theta}(x))$$
  
=  $-y \log(1 + e^{-\theta^{T}x}) + (1 - y)(-\theta^{T}x) - (1 - y) \log(1 + e^{-\theta^{T}x})$   
=  $-\log(1 + e^{-\theta^{T}x}) - (1 - y)(\theta^{T}x)$ 

We used  $1 - h_{\theta}(x) = \frac{e^{-\theta^{T}x}}{1 - e^{-\theta^{T}x}}$ . We now compute the derivative of this expression wrt  $\theta$  and get:

$$\frac{e^{-\theta^T x}}{1+e^{-\theta^T x}}x - (1-y)x = (y - h_{\theta}(x))x$$

## Perceptron Learning Algorithm

- Modify link function to output either 0 or 1.
- Make g to be a threshold function
- Then use same  $h_{\theta}(x) = g(\theta^T x)$  using this g
- Follow the same update rule for  $\boldsymbol{\theta}$

$$g(z) = \begin{cases} 1 & \text{if } z \ge 0\\ 0 & \text{if } z < 0 \end{cases}$$

## Summary of Introduction to Classification

We used the principle of maximum likelihood (and a probabilistic model) to extend to classification.

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- We used the principle of maximum likelihood (and a probabilistic model) to extend to classification.
- We developed logistic regression from this principle.
  - Logistic regression is widely used today.
- We noticed a familiar pattern: take derivatives of the likelihood, and the derivatives had this (hopefully) intuitive "misprediction form"

## **Optimization Method Summary**

	Compute per Step	Number of Steps
Method		to convergence
SGD	$\theta(d)$	≈ € <sup>-2</sup>
Minibatch SGD		
GD	$\theta(nd)$	≈ <b>€</b> <sup>-1</sup>
Newton	$\Omega(nd^2)$	$\approx \log(1/\epsilon)$

- In classical stats, d is small (< 100), n is often small, and exact parameters matter
- In modern ML, d is huge (billions, trillions), n is huge (trillions), and parameters used only for prediction
  - These are approximate number of computing steps
  - Convergence happens when loss settles to within an error range around the final value.
  - Newton would be very fast, where SGD needs a lot of step, but individual steps are fast, makes up for it
- As a result, (minibatch) SGD is the workhorse of ML.

## **Classification Lecture Summary**

- We saw the differences between classification and regression.
- We learned about a principle for probabilistic interpretation for linear regression and classification: Maximum Likelihood.
  - We used this to derive logistic regression.
  - The Maximum Likelihood principle will be used again next lecture (and in the future)