Lecture Two Supervised Learning: Regression

Adapted from Chris Ré Stanford ML

Supervised Learning and Linear Regression

- Definitions
- ► Linear Regression
- Batch and Stochastic Gradient
- ► Normal Equations

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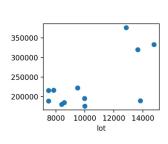
- ▶ If \mathcal{Y} is continuous, then called a *regression problem*.
- \triangleright If \mathcal{Y} is discrete, then called a *classification problem*.



Our first example: Regression using Housing Data.

Example Data (Housing Prices from Ames Dataset from Kaggle)

	SalePrice	Lot.Area
4	189900	13830
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9	189000	7500
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12	180400	8402
22	216000	7500
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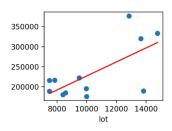
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Notice the prediction is defined by the parameters θ_0 and θ_1 . This is a huge reduction in the space of functions!

Simple Line Fit

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We add *features* (bedrooms and lot size) to incorporate more information about houses.

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With the convention that $x_0 = 1$ we can write:

$$h(x) = \sum_{j=0}^{3} \theta_j x_j$$

Vector Notation for Prediction

	size	bedrooms	lot size		Price
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We write the vectors as (important notation)

$$\theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix} \text{ and } x^{(1)} = \begin{pmatrix} x_0^{(1)} \\ x_1^{(1)} \\ x_2^{(1)} \\ x_3^{(1)} \end{pmatrix} = \begin{pmatrix} 1 \\ 2104 \\ 4 \\ 45 \end{pmatrix} \text{ and } y^{(1)} = 400$$

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We call θ parameters, $x^{(i)}$ is the input or the **features**, and the output or **target** is $y^{(i)}$. To be clear,

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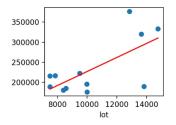
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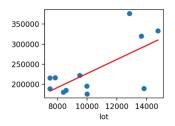
We have n examples (i.e., $i=1,\ldots,n$). There are d features so $x^{(i)}$ and θ are d+1 dimensional (since $x_0=1$).

Visual version of linear regression



Let $h_{\theta}(x) = \sum_{j=0}^{d} \theta_{j} x_{j}$ want to choose θ so that $h_{\theta}(x) \approx y$.

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Let $h_{\theta}(x) = \sum_{j=0}^{d} \theta_{j} x_{j}$ want to choose θ so that $h_{\theta}(x) \approx y$. One popular idea called **least squares**

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{n} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^{2}.$$

Choose

$$\theta = \underset{\theta}{\operatorname{argmin}} J(\theta).$$

Linear Regression Summary

- ▶ We saw our first hypothesis class *affine* or *linear* functions.
- ► We refreshed ourselves on notation and introduced terminology like **parameters**, **features**, etc.
- ▶ We saw this paradigm that a "good" hypothesis is some how one that *is close to* the data (objective function *J*).

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- Next, we'll see how to solve these equations.

Solving the least squares optimization problem.

Gradient Descent

$$\theta^{(0)} = 0$$

$$\theta_j^{(t+1)} = \theta_j^{(t)} - \alpha \frac{\partial}{\partial \theta_j} J(\theta^{(t)}) \qquad \text{for } j = 0, \dots, d.$$

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Note that α is called the **learning rate** or **step size**.

Let's compute the derivatives...

$$\frac{\partial}{\partial \theta_j} J(\theta^{(t)}) = \sum_{i=1}^n \frac{1}{2} \frac{\partial}{\partial \theta_j} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right)^2$$
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For our particular h_{θ} we have:

$$h_{\theta}(x) = \theta_0 x_0 + \theta_1 x_1 + \dots + \theta_d x_d$$
 so $\frac{\partial}{\partial \theta_j} h_{\theta}(x) = x_j$

Thus, our update rule for component j can be written:

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We write this in *vector notation* for j = 0, ..., d as:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha \sum_{i=1}^{n} \left(h_{\theta}(x^{(i)}) - y^{(i)} \right) x^{(i)}.$$

Saves us a lot of writing! And easier to understand ... eventually.

Batch Versus Stochastic Minibatch: Motivation

Consider our update rule:

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- ▶ In some modern applications (more later) *n* may be in the billions or trillions!
 - ► E.g., we try to "predict" every word on the web.
- ► Idea Sample a few points (maybe even just one!) to approximate the gradient called Stochastic Gradient (SGD).
 - SGD is the workhorse of modern ML, e.g., pytorch and tensorflow.

Stochastic Minibatch

- ▶ We randomly select a **batch** of $B \subseteq \{1, ..., n\}$ where |B| < n.
- ► We approximate the gradient using just those *B* points as follows (vs. gradient descent)

$$\frac{1}{|B|} \sum_{j \in B} \left(h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)} \text{ v.s. } \frac{1}{n} \sum_{j=1}^{n} \left(h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

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► So our update rule for SGD is:

All minibatches are used for each iteration, or epoch and then start the next one $% \left\{ 1,2,\ldots ,n\right\}$

$$\theta^{(t+1)} = \theta^{(t)} - \alpha_B \sum_{j \in B} \left(h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

▶ NB: scaling of |B| versus n is "hidden" inside choice of α_B .



Stochastic Minibatch vs. Gradient Descent

► Recall our rule *B* points as follows:

$$\theta^{(t+1)} = \theta^{(t)} - \alpha_B \sum_{j \in B} \left(h_{\theta}(x^{(j)}) - y^{(j)} \right) x^{(j)}.$$

- ▶ If $|B| = \{1, ..., n\}$ (the whole set), then they coincide.
- ► Smaller *B* implies a lower quality approximation of the gradient (higher variance).
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- Nevertheless, it may actually converge faster! (Case where the dataset has many copies of the same point-extreme, but lots of redundancy)
- ► In practice, choose *B* proportional to what works well on modern parallel hardware (GPUs).

Summary of this Subsection of Optimization

- Our goal was to optimize a loss function to find a good predictor.
- We learned about gradient descent and the workhorse algorithm for ML, Stochastic Gradient Descent (SGD).
- ▶ We touched on the tradeoffs of choosing the right batch size.

Summary from Today

- ▶ We saw a lot of notation
- ► We learned about linear regression: the model, how to solve, and more.
- ▶ We learned the workhorse algorithm for ML called **SGD**.
- Next time: Classification!